

The Effects of Transformations on the Optimal Set in Interval Linear Programming

Elif Garajová¹ (with Milan Hladík¹ & Miroslav Rada²)

¹Department of Applied Mathematics, Faculty of Mathematics and Physics,
Charles University

²Faculty of Informatics and Statistics, University of Economics, Prague

Consider a linear programming problem...

$$\text{minimize } c^T x \text{ subject to } Ax \leq b$$

Interval Linear Programming

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estimating the future

$$\text{€}25.6 \leq c \leq \text{€}27.1$$

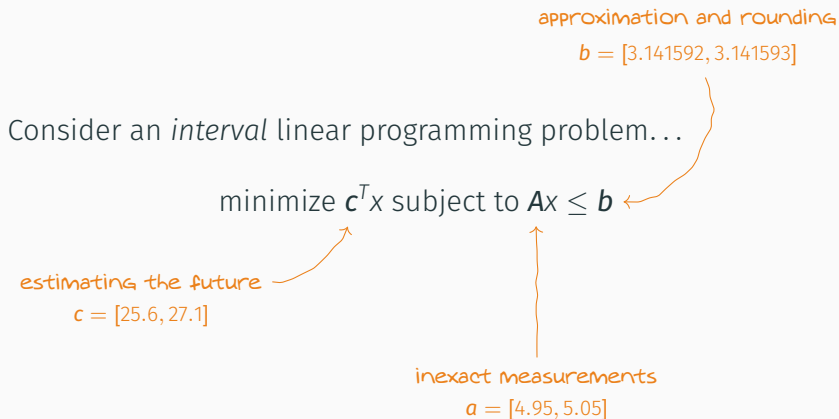
inexact measurements

$$a = 5 \pm 0.05g$$

approximation and rounding

$$b \approx 3.14159$$

Interval Linear Programming



Interval Linear Programming: Definitions

- An **interval linear program** is a family of linear programs

$$\text{minimize } c^T x \text{ subject to } x \in \mathcal{M}(A, b),$$

where $A \in \mathbf{A}$, $b \in \mathbf{b}$, $c \in \mathbf{c}$ and $\mathcal{M}(A, b)$ is the feasible set.

- A linear program in the family is called a **scenario**.
- A vector x is a **(weakly) feasible/optimal** solution to the interval program, if x is a feasible/optimal solution for some scenario with $A \in \mathbf{A}$, $b \in \mathbf{b}$, $c \in \mathbf{c}$.

Interval Linear Programming: Example

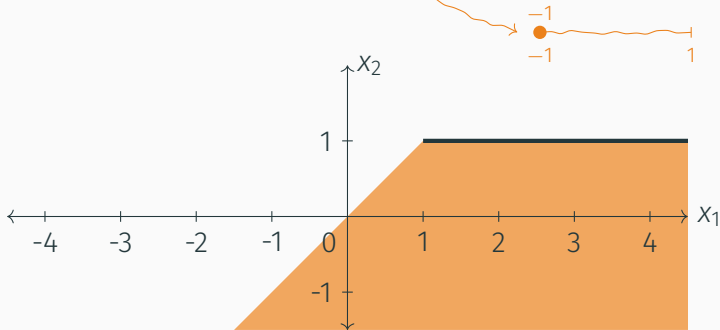
$$\begin{array}{ll} \text{maximize} & x_2 \\ \text{subject to} & [-1, 1]x_1 + x_2 \leq 0 \\ & x_2 \leq 1 \end{array}$$

- What are the possible feasible solutions?
- Which solutions are optimal for some scenario?
- What is the set/range of all optimal values?

Interval Linear Programming: Example

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 $x_2 \leq 1$

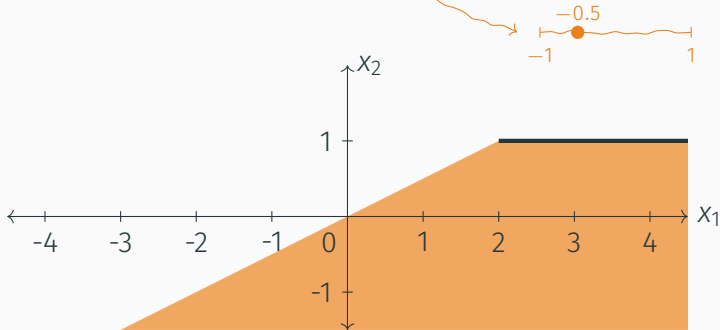
Let's traverse through this!



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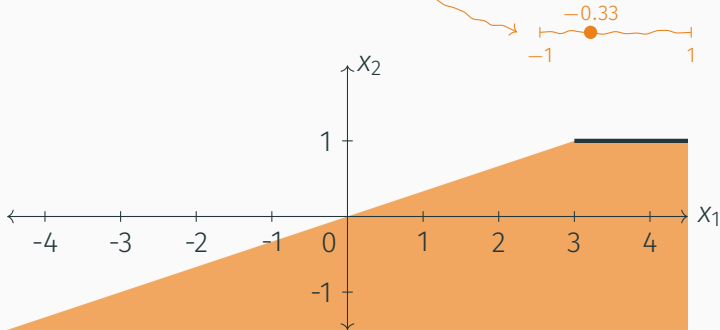
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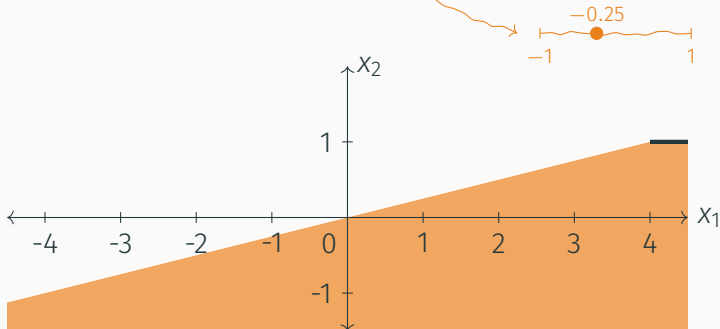
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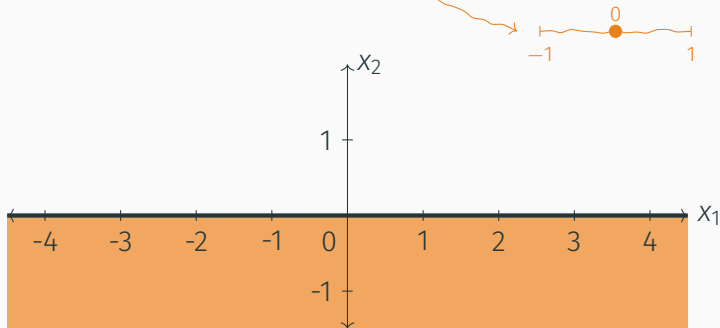
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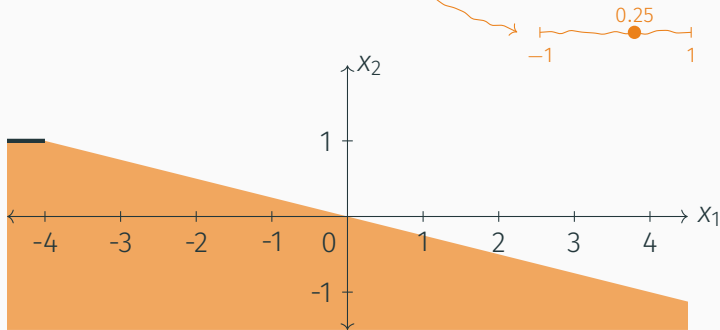
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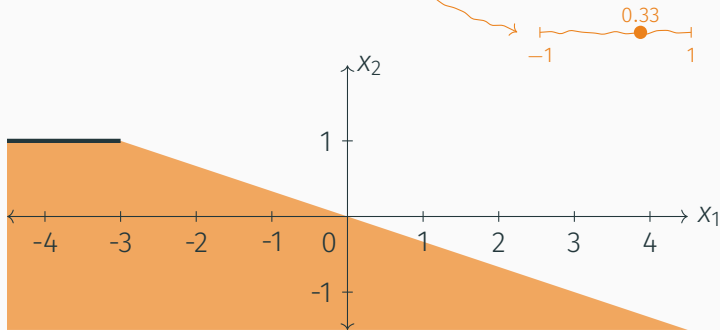
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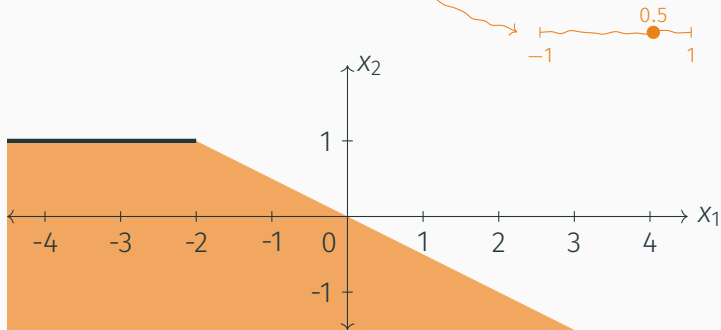
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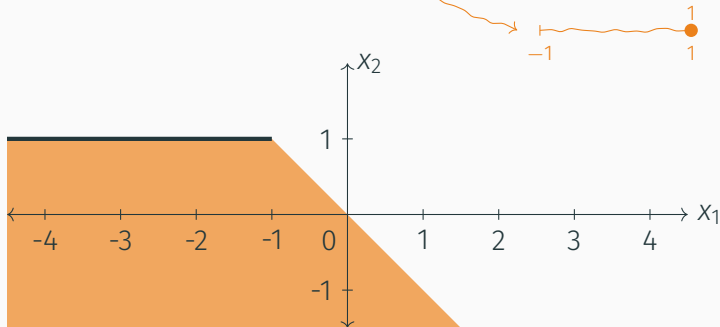
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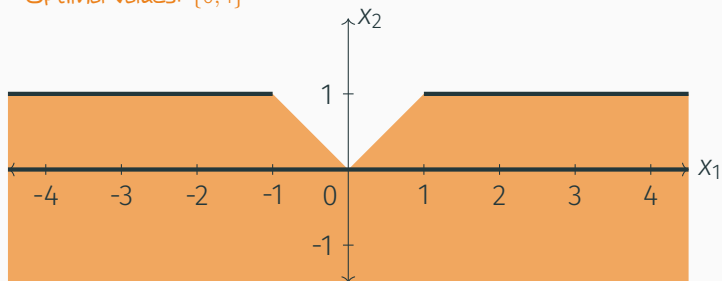
Let's traverse through this!



Interval Linear Programming: Example

$$\begin{aligned} &\text{maximize} && x_2 \\ &\text{subject to} && [-1, 1]x_1 + x_2 \leq 0 \\ & && x_2 \leq 1 \end{aligned}$$

Optimal values: $\{0, 1\}$



Overview of Basic Results

Feasible solutions:

- **Oettli-Prager:** x solves $Ax = b \Leftrightarrow |A_c x - b_c| \leq A_\Delta |x| + b_\Delta$
- **Gerlach:** x solves $Ax \leq b \Leftrightarrow A_c x - A_\Delta |x| \leq \bar{b}$

Optimal values:

- Best optimal value (inequalities):

For each $s \in \{\pm 1\}^n$ solve

$$\min (c_c - D_s c_\Delta)^T x \text{ s. t. } (A_c - A_\Delta D_s)x \leq \bar{b}, D_s x \geq 0$$

- Worst optimal value (inequalities):

$$\max \underline{b}^T y \text{ s. t. } \bar{A}^T y \leq \bar{c}, \underline{A}^T y \geq \underline{c}, y \leq 0$$

Optimal solutions:

- Special cases, approximations, ...

Dependency Problem (I)

$$\begin{array}{ll} \max & x_1 \\ \text{s. t.} & [0, 1]x_1 - x_2 = 0, \\ & x_2 \leq 1, \\ & x_1, x_2 \geq 0. \end{array}$$

Optimal set: $\{(x_1, x_2) \in \mathbb{R}^2 : x_1 \in [1, \infty) \text{ and } x_2 = 1\}$

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$$\begin{array}{ll} \max & x_1 \\ \text{s. t.} & 1x_1 - x_2 \leq 0, \\ & 0x_1 - x_2 \geq 0, \\ & x_2 \leq 1, \\ & x_1, x_2 \geq 0. \end{array}$$

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The solution $(0, 0)$ is now optimal, too!

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The solution $(0, 0)$ is now optimal, too!

...But the feasible set is the same! (Li, 2015)

Dependency Problem (II)

Example (Hladík, 2012)

$$[1, 2]x \leq 2 \quad \rightarrow \quad [1, 2]x^+ - [1, 2]x^- \leq 2, \quad x^+, x^- \geq 0$$

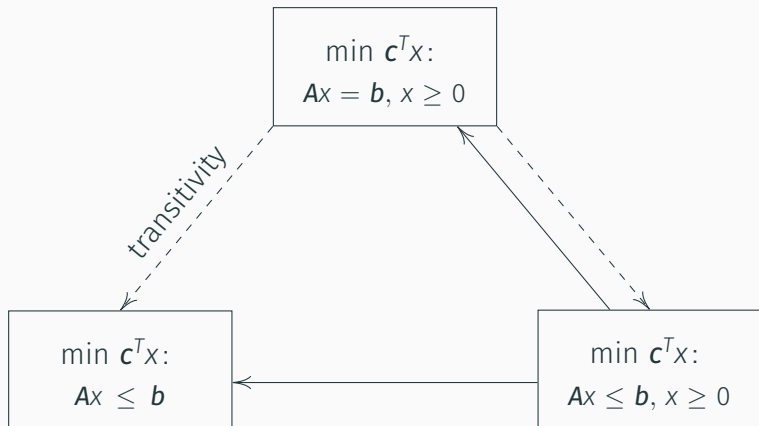
Original feasible set: $(-\infty, 2]$

Consider the new scenario $1x^+ - 2x^- \leq 2, x^+, x^- \geq 0$...

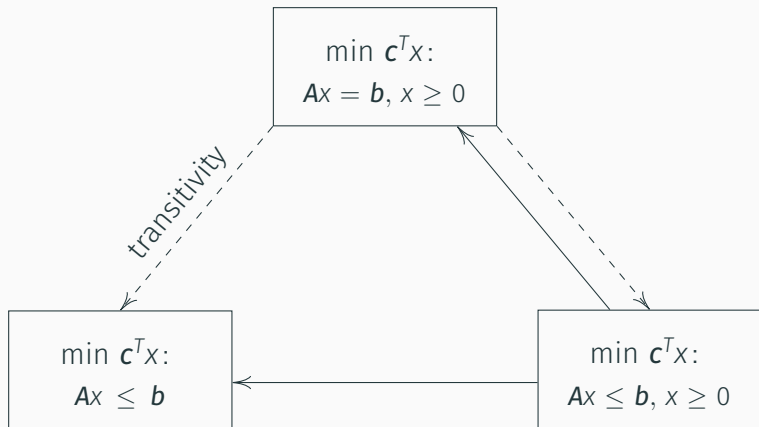
All real numbers are now feasible solutions, because we can express any real x as $x = x^+ - x^-$, where

$$x^+ = \max(2x, 0) \text{ and } x^- = |x|.$$

Transformations: The General Case



Transformations: The General Case



What if A is fixed?

Splitting Equations into Inequalities

Theorem 1

The optimal solution set of the interval linear program

$$\min \mathbf{c}^T \mathbf{x}: A\mathbf{x} = \mathbf{b}, \mathbf{x} \geq 0$$

is equal to the optimal solution set of the program

$$\min \mathbf{c}^T \mathbf{x}: A\mathbf{x} \leq \mathbf{b}_1, -A\mathbf{x} \leq -\mathbf{b}_2, \mathbf{x} \geq 0$$

with $\mathbf{b}_1 = \mathbf{b}_2 = \mathbf{b}$.

Splitting Equations into Inequalities

Theorem 1

The optimal solution set of the interval linear program

$$\min \mathbf{c}^T x: Ax = \mathbf{b}, x \geq 0$$

is equal to the optimal solution set of the program

$$\min \mathbf{c}^T x: Ax \leq \mathbf{b}_1, -Ax \leq -\mathbf{b}_2, x \geq 0$$

with $\mathbf{b}_1 = \mathbf{b}_2 = \mathbf{b}$.

Proof idea:

x^* optimal for scenario $\min \mathbf{c}^T x: \mathbf{b}_2 \leq Ax \leq \mathbf{b}_1, x \geq 0$

$\Rightarrow Ax^* = \mathbf{b}_3 \in \mathbf{b} \Rightarrow x^*$ optimal for $\min \mathbf{c}^T x: Ax = \mathbf{b}_3, x \geq 0$

Theorem 2

Let \mathcal{S} denote the optimal solution set of $\min \mathbf{c}^T \mathbf{x} : \mathbf{A}\mathbf{x} \leq \mathbf{b}$ and let \mathcal{S}' be the optimal solution set of the program

$$\min \mathbf{c}_1^T \mathbf{x}^+ - \mathbf{c}_2^T \mathbf{x}^- : \mathbf{A}\mathbf{x}^+ - \mathbf{A}\mathbf{x}^- \leq \mathbf{b}, \mathbf{x}^+, \mathbf{x}^- \geq 0$$

with $\mathbf{c}_1 = \mathbf{c}_2 = \mathbf{c}$. Then, the following properties hold:

- If $\mathbf{x} \in \mathcal{S}$, then there is $(\mathbf{x}^+, \mathbf{x}^-) \in \mathcal{S}'$ with $\mathbf{x} = \mathbf{x}^+ - \mathbf{x}^-$.
- If $(\mathbf{x}^+, \mathbf{x}^-) \in \mathcal{S}'$, then $\mathbf{x}^+ - \mathbf{x}^- \in \mathcal{S}$.

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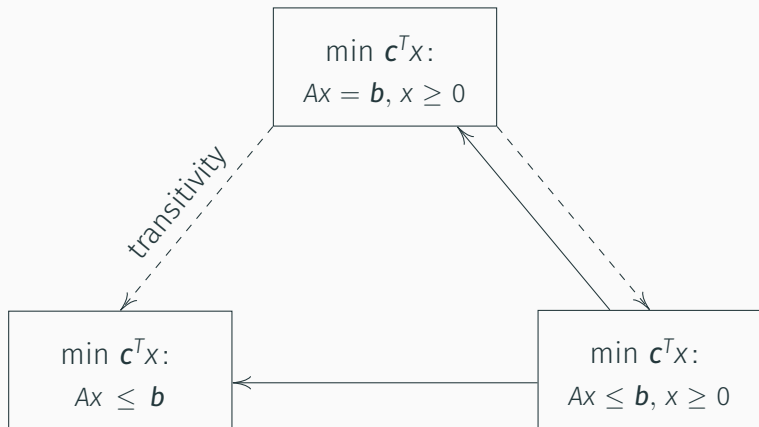
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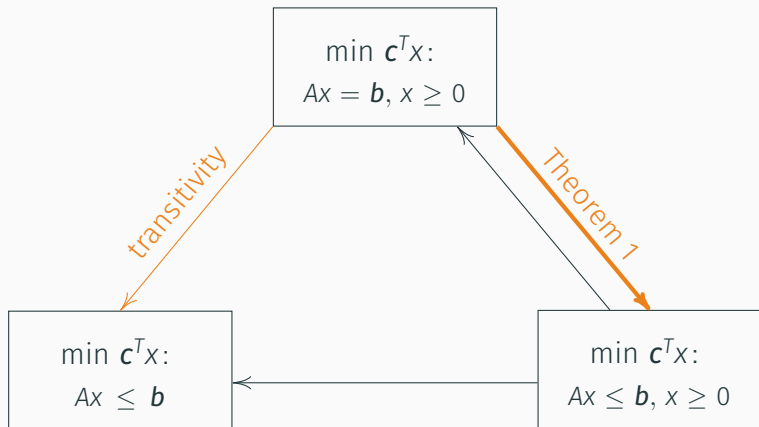
Proof idea:

For an optimal \mathbf{x}^* , we have by dual feasibility some \mathbf{y}^* with $\mathbf{A}^T \mathbf{y}^* = \mathbf{c}_3 \in [\mathbf{c}_2, \mathbf{c}_1] \subseteq \mathbf{c}$. Then, \mathbf{x}^* is optimal for $\min \mathbf{c}_3^T \mathbf{x} : \mathbf{A}\mathbf{x} \leq \mathbf{b}$.

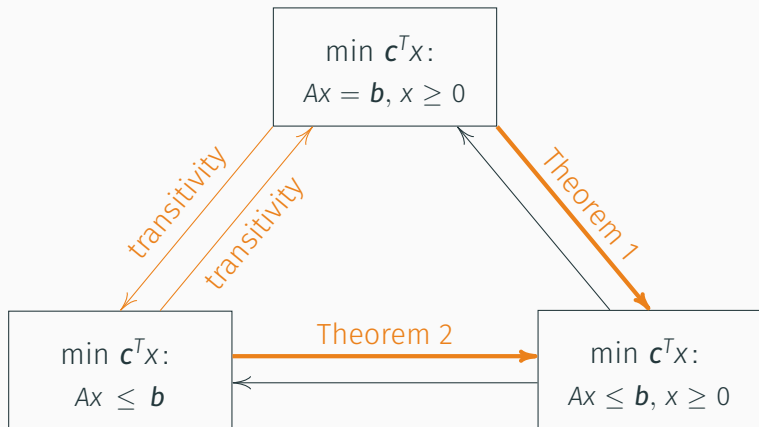
Transformations: The Special Case



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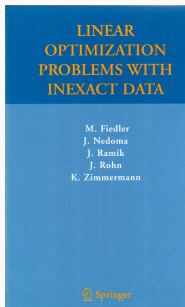


Transformations: The Special Case



Conclusion

- In interval linear programming, the basic transformations may change the feasible/optimal set and other properties of a program.
- We have shown that the transformations do not affect the optimal set for problems with a fixed coefficient matrix (they may still change other properties!).
- Thus, we can directly generalize results concerning the optimal set of a particular type of programs to other types.



Linear Optimization Problems with Inexact Data (2006). Authors: M. Fiedler, J. Nedoma, J. Ramík, J. Rohn, K. Zimmermann

Interval linear programming: A survey (2012).
M. Hladík. Linear Programming – New Frontiers
in Theory and Applications.

Chapter 7

INTERVAL LINEAR PROGRAMMING: A SURVEY

Milan Hladík
Charles University, Faculty of Mathematics and Physics,
Department of Applied Mathematics,
Michovského nám. 25, 115 08, Prague, Czech Republic

Abstract

Inequality is a common phenomenon in practice. This is manifested either as
uncertain input data or as imprecise model parameters. Interval
linear programming has led to satisfactory results. Unfortunately, there is still the
interval analysis of linear problems, each of them has some pros and cons. In
this paper we compare these two approaches and point out the advantages and
the problems. The general methodology and applications are also discussed. As
the result we investigate the problems of optimality tests, non-robust optimal
objective values, stability in. Complete codes and datasets are available at
preprints.ceremade.fr and another one at 10P.hard

The approach is a general and generalized the standard interval analysis.
In interval analysis, we consider systems of only one parameter, which is very
convenient. In the other hand, interval approach based optimal analysis or better
understanding of input parameters. We present a new approach of the above
tasks with an algorithm, and discuss the way of its state changing problem.

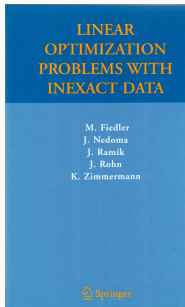
MSC2010: 52J15, 90C10, 90C30

Keywords: Linear interval systems, linear programming, interval analysis, optimal value
tests, interval matrix, non-robust AWP

Mathematics Subject Classification: 90C10, 90C30, 90C40

1. Introduction

Many practical problems are solved by linear programming. Since such problems are
subject to uncertainties, their errors, measurements and estimations, we have to take it as
interval analysis. Interval analysis is a powerful tool for the analysis of the above
tasks with an algorithm, and discuss the way of its state changing problem.



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Abstract

Inequality is a common phenomenon in practice. Since measurement errors are inevitable, interval programming is a natural way to model optimization problems. Interval linear programming has had a remarkable success. Unfortunately, there is still the main obstacle. Theoretical results are hard to solve, so far, by introducing progressively interval analysis or fuzzy methods, each of them has some pros and cons. In this paper, we explore these two paths to see what opportunities are available, and to provide the general introduction and preliminary results also. In the end, we investigate the problems of open-line tools, how stability optimal solutions, stability in Complete case and duality, and some other problems solvable while another are NP-hard.

The approach is a general and generalized the standard stability analysis. In interval analysis, we consider systems of only one parameter, which is very common. In the other hand, interval optimization based approach can be used simultaneously in several parameters. We provide a new approach of the above results with an example, and discuss the way of by using changing problem.

MSC2010: 52.15, 90.80, 90.85

Keywords: Linear interval systems, linear programming, interval analysis, optimal value range, interval matrix, non-stability AMPL Solver Classification: WCL1, WCL2, WCL3

1. Introduction

Many practical problems are solved by linear programming. Since such problems are subject to uncertainties, there are errors, measurement and estimation, we have to face it as

Thank you for your attention!